# Complex structures of a twenty dimensional family of Calabi-Yau 3-folds 

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#### Abstract

In this paper, we classify all isomorphic classes of a family of Calabi-Yau 3-folds with 20 parameters. In addition, we show that the isomorphisms form a finite group. The invariants under the action of this group are calculated by introducing the so-called DS-graph.


## 1. Introduction

A Calabi-Yau manifold is a manifold with trivial canonical bundle. It plays an important role in theoretical physics. In super-string theory, it is conjectured that the extra dimensions of space-time take the form of a compact complex 3-dimensional Calabi-Yau manifold. Non-singular quintic 3-folds are Calabi-Yau manifolds. It is a fundamental important question in both mathematics and theoretical physics to determine when two given quintic 3 -folds have the same complex structure. Such a question seems to be out of reach by 19th century invariant theory or modern geometric invariant theory. Candelas, Ossa, Green and Parkers [1] studied the following one dimensional family of Calabi-Yau 3 -folds

$$
X_{t}:=\left\{\left(x_{i}\right) \in \mathbb{C P}^{4}: x_{1}^{5}+x_{2}^{5}+x_{3}^{5}+x_{4}^{5}+x_{5}^{5}+t x_{1} x_{2} x_{3} x_{4} x_{5}=0\right\}
$$

in detail by means of the period map. Chen et al. [3, 4] generalize it to the families

$$
X_{t}^{(n)}:=\left\{\left(x_{i}\right) \in \mathbb{C P}^{n-1}: x_{1}^{n}+x_{2}^{n}+\ldots+x_{n}^{n}+t x_{1} x_{2} \cdots x_{n}=0\right\}
$$

with $n \geqslant 3$. The purpose of this paper is to study the complex structures of a distinguished class of 20-dimensional family of Calabi-Yau 3-folds $\left\{V\left(f_{\mathbf{t}}\right)\right\}$

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with parameter $\mathbf{t}:=\left(t_{i, j}\right)$ for $i, j=1,2,3,4,5$ and $i \neq j$, where

$$
f_{\mathbf{t}}:=f_{\mathbf{t}}(x):=x_{1}^{5}+x_{2}^{5}+x_{3}^{5}+x_{4}^{5}+x_{5}^{5}+\sum_{i \neq j} t_{i, j} x_{i}^{4} x_{j} .
$$

Our main goal is to completely distinguish these complex structures and find out the moduli and modular group of this family by introducing a novel simple method.

Let $G$ be a finite group $G=S_{5} \ltimes \mathbb{Z}_{5}^{5}$. The group operation is given by

$$
\begin{aligned}
& \left(\tau, b_{1}, b_{2}, \ldots, b_{5}\right) \cdot\left(\sigma, a_{1}, a_{2}, \ldots, a_{5}\right) \\
& \quad:=\left(\tau \sigma, b_{\sigma(1)}+a_{1}, b_{\sigma(2)}+a_{2}, \ldots, b_{\sigma(5)}+a_{5}\right)
\end{aligned}
$$

for $\left(\tau, b_{1}, b_{2}, \ldots, b_{5}\right),\left(\sigma, a_{1}, a_{2}, \ldots, a_{5}\right) \in G$. We define the group action on variables $t_{i, j}$ as follows. Fix $\eta$ a 5 -th primary root of 1 . Then

$$
\left(\sigma, a_{1}, a_{2}, \ldots, a_{5}\right) \cdot t_{i, j}:=\eta^{a_{i}-a_{j}} t_{\sigma(i), \sigma(j)} .
$$

When restrict the parameter $\mathbf{t}$ to a specific affine open subset, the main result of this paper states that the Calabi-Yau 3-fold $V\left(f_{\mathbf{t}}\right)$ is biholomorphic to $V\left(f_{\mathbf{t}^{\prime}}\right)$ if and only if there exists some element $g \in G$ such that $g \cdot t_{i, j}=t_{i, j}^{\prime}$ for $i, j=1,2, \ldots, 5$ and $i \neq j$. Moreover, we construct a basis of $\mathbb{C}\left[t_{i j}\right]^{G}$ expressed as the polynomials $\sum_{\text {sym }} M\left(V, E_{d}, E_{s}\right)$, where ( $V, E_{d}, E_{s}$ ) ranges over all DS-graphs. See the precise statement in Section 3 .

## 2. Isomorphic class of family $\left\{V\left(f_{\mathrm{t}}\right)\right\}$

In this section, we investigate the complex structures of the family $\left\{V\left(f_{\mathbf{t}}\right)\right\}$.
Let $x=\left(x_{1}, x_{2}, \ldots, x_{5}\right)$. The derivative with respect to $x_{i}$ will be shortly denoted by $\partial_{i}$. Let $I_{\mathbf{t}}$ be the ideal of $\mathbb{C}[x]$ generated by $\partial_{i, j} f_{\mathbf{t}}: i, j=$ $1,2, \ldots, 5$. We introduce the algebra

$$
A_{\mathbf{t}}:=\mathbb{C}[x] / I_{\mathbf{t}}
$$

Observe that $A_{\mathbf{t}}$ is an invariant of the $V\left(f_{\mathbf{t}}\right)$. We require the parameters $t_{i, j}$ verify the main assumption that ideal $I_{\mathbf{t}}$ is generated by $x_{i}^{3}$ and $\sum_{k \neq i} t_{i, k} x_{i}^{2} x_{k}$ for $i=1,2, \ldots, 5$. We shall emphasize that this assumption holds generically. To see this, we deduce the following lemma.

Lemma 1. Let $(i, j, k, l, m)$ be an ordering of $\{1,2,3,4,5\}$. Suppose that the coefficients $t_{i, j}$ satisfy the following conditions

1) $t_{i, j} t_{j, k} t_{k, i}+t_{j, i} t_{k, j} t_{i, k} \neq 0$.
2) $t_{l, i}, t_{l, j}, t_{l, k}$ do not vanish simultaneously.
3) $t_{m, i}, t_{m, j}, t_{m, k}$ do not vanish simultaneously.

Then the ideal $I_{\mathbf{t}}$ is finite generated by $x_{i}^{3}$ and $\sum_{k \neq i} t_{i, k} x_{i}^{2} x_{k}$ for $i=$ $1,2, \ldots, 5$.

Proof. By direct computation, the second derivatives $\partial_{i, j} f_{\mathbf{t}}$ are expressed as

$$
\partial_{i, j} f_{\mathbf{t}}=4 t_{i, j} x_{i}^{3}+4 t_{j, i} x_{j}^{3} \text { for } i \neq j
$$

and

$$
\partial_{i, i} f_{\mathbf{t}}=20 x_{i}^{3}+12 \sum_{k \neq i} t_{i, k} x_{i}^{2} x_{k}
$$

The first condition of this lemma and the expressions of $\partial_{i, j} f_{\mathbf{t}}, \partial_{j, k} f_{\mathbf{t}}, \partial_{k, i} f_{\mathbf{t}}$ imply $x_{i}^{3}, x_{j}^{3}, x_{k}^{3}$ are contained in $I_{\mathbf{t}}$. The rest conditions yield that $x_{l}^{3}, x_{m}^{3}$ are also contained in $I_{\mathbf{t}}$. The proof of our lemma is completed by applying the expressions of $\partial_{i, i}\left(f_{\mathbf{t}}\right)$ with $i=1,2, \ldots, 5$.

Let $T=\mathbb{C}^{5}$ be a $\mathbb{C}$-vector space spanned by $x_{i}$ for $i=1,2, \ldots, 5$. For $\xi \in T$, we denote $\bar{\xi} \in A_{\mathbf{t}}$. Define subset of $T$ by $S_{\mathbf{t}}:=\left\{\xi \in T: \bar{\xi}^{3}=0\right\}$. Now we wish to determine the set $S_{\mathrm{t}}$.

Lemma 2. Assume that the main assumption of $\mathbf{t}$ holds. Then the set $S_{\mathbf{t}}$ is independent on the coefficients $\mathbf{t}$. Moreover, it is given by coordinate axes. That is $S_{\mathbf{t}}=\left\{\lambda x_{i}: \lambda \in \mathbb{C}, i=1,2, \ldots, 5\right\}$.

Proof. The fact $\bar{\xi}^{3}=0$ means that $\xi^{3}$ is generated by $x_{i}^{3}$ and $\sum_{k \neq i} t_{i, k} x_{i}^{2} x_{k}$. Write $\xi=\alpha_{1} x_{1}+\alpha_{2} x_{2}+\alpha_{3} x_{3}+\alpha_{4} x_{4}+\alpha_{5} x_{5}$. Then this means

$$
\begin{equation*}
\left(\sum_{i=1}^{5} \alpha_{i} x_{i}\right)^{3}=\sum_{i=1}^{5} \beta_{i} x_{i}^{3}+\sum_{i=1}^{5} \gamma_{i} \sum_{k \neq i} t_{i, k} x_{i}^{2} x_{k} \tag{1}
\end{equation*}
$$

with some coefficients $\beta_{i}, \gamma_{i}$. By comparing coefficients, we see that at most two $\alpha_{i}$ 's are nonzero. Without loss generality, we assume that $\alpha_{1}$ and $\alpha_{2}$ are
nonzero. Thus, Equation (1) becomes

$$
\begin{aligned}
\left(\alpha_{1} x_{1}+\alpha_{2} x_{2}\right)^{3}= & \beta_{1} x_{1}^{3}+\beta_{2} x_{2}^{3} \\
& +\gamma_{1}\left(t_{1,2} x_{1}^{2} x_{2}+t_{1,3} x_{1}^{2} x_{3}+t_{1,4} x_{1}^{2} x_{4}+t_{1,5} x_{1}^{2} x_{5}\right) \\
& +\gamma_{2}\left(t_{2,1} x_{2}^{2} x_{1}+t_{2,3} x_{2}^{2} x_{3}+t_{2,4} x_{2}^{2} x_{4}+t_{2,5} x_{2}^{2} x_{5}\right)
\end{aligned}
$$

This implies $t_{1, k}=t_{2, k}=0$ for $k=3,4,5$. The fact $x_{i}^{3} \in I_{\mathbf{t}}$ implies $t_{1,2}=$ $t_{2,1}=0$. Hence, we obtain $\left(\alpha_{1} x_{1}+\alpha_{2} x_{2}\right)^{3}=\beta_{1} x_{1}^{3}+\beta_{2} x_{2}^{3}$. Therefore, we have $\alpha_{1}=0$ or $\alpha_{2}=0$. In conclusion, we find that $\xi=\lambda x_{i}$ for some constant $\lambda$.

Theorem 3. Assume that $\mathbf{t}$ and $\mathbf{t}^{\prime}$ satisfy the main assumption. Then the linear isomorphism from $V\left(f_{\mathbf{t}}^{\prime}\right)$ to $V\left(f_{\mathbf{t}}\right)$ is generated by permutations on the subscripts of $t_{i, j}$ and the scaling $x_{i} \mapsto x_{i} \eta_{i}$ such that $\eta_{i}^{5}=1$ and $t_{i, j}^{\prime}=$ $t_{i, j} \eta_{i} \eta_{j}^{-1}$.

Proof. Suppose that $V\left(f_{\mathbf{t}}\right)$ is isomorphic to $V\left(f_{\mathbf{t}}^{\prime}\right)$. So we have $A_{\mathbf{t}} \cong A_{\mathbf{t}^{\prime}}$. Hence, $S_{\mathrm{t}}$ maps isomorphically to $S_{\mathrm{t}^{\prime}}$. Denote by $\phi$ the isomorphism from $V\left(f_{\mathbf{t}}^{\prime}\right)$ to $V\left(f_{\mathbf{t}}\right)$. From Lemma 2, we can assume that $\phi\left(x_{i}\right):=\lambda_{i} x_{i}$ for some constant $\lambda_{i}$ with $i=1,2, \ldots, 5$. By assumption, we have $f_{\mathbf{t}^{\prime}}(\phi(x))=\lambda_{0}^{5} f_{\mathbf{t}}(x)$ for some complex number $\lambda_{0}$. Then

$$
\begin{aligned}
f_{\mathbf{t}^{\prime}}(\phi(x)) & =\sum_{i=1}^{5} \phi\left(x_{i}\right)^{5}+\sum_{i \neq j} t_{i, j}^{\prime} \phi\left(x_{i}\right)^{4} \phi\left(x_{j}\right) \\
& =\sum_{i=1}^{5} \lambda_{i}^{5} x_{i}^{5}+\sum_{i \neq j} t_{i, j}^{\prime} \lambda_{i}^{4} \lambda_{j} x_{i}^{4} x_{j} \\
& =\sum_{i=1}^{5} \lambda_{0}^{5} x_{i}^{5}+\lambda_{0}^{5} \sum_{i \neq j} t_{i, j} x_{i}^{4} x_{j} .
\end{aligned}
$$

This implies $\lambda_{i}^{5}=\lambda_{0}^{5}$ and $\lambda_{i}^{4} \lambda_{j} t_{i, j}^{\prime}=\lambda_{0}^{5} t_{i, j}$. Put $\eta_{i}:=\lambda_{i} / \lambda_{0}$. Then $t_{i, j}^{\prime}=$ $\eta_{i} \eta_{j}^{-1} t_{i, j}$. Conversely, it is easy to verify that permutation on the subscripts and scaling defined above map isomorphically from $V\left(f_{\mathbf{t}^{\prime}}\right)$ to $V\left(f_{\mathbf{t}}\right)$.

Let $G$ be a finite group $G=S_{5} \ltimes \mathbb{Z}_{5}^{5}$. Fix $\eta$ a 5 -th primary root of 1 . According to previous theorem, it is natural to define the group action on
variables $t_{i, j}$ as

$$
g \cdot t_{i, j}:=\eta^{a_{i}-a_{j}} t_{\sigma(i), \sigma(j)}
$$

for $g=\left(\sigma, a_{1}, a_{2}, \ldots, a_{5}\right) \in G$. Applying the previous theorem, we obtain the following corollary.

Corollary 4. Assume that $\mathbf{t}$ and $\mathbf{t}^{\prime}$ satisfy the main assumption. Then $V\left(f_{\mathbf{t}}\right)$ and $V\left(f_{\mathbf{t}^{\prime}}\right)$ are isomorphic if and only if there exists some element $g \in G$, such that $g \cdot t_{i, j}=t_{i, j}^{\prime}$ for $i, j=1,2, \ldots, 5$ and $i \neq j$.

## 3. Directed graph

In this section, we establish a relationship between invariants of $V\left(f_{\mathbf{t}}\right)$ and some directed graphs. The canonical directed graph consists of the set of vertices $V$ and the set of directed edges $E$. In order to investigate the invariances of the family $\left\{V\left(f_{\mathbf{t}}\right)\right\}$, we introduce the new kind of directed graphs which shall be called DS-graph. It consists of the set of vertices $V$ and the set of dashed edges $E_{d}$ and the set of (multiple) solid edges $E_{s}$ such that

1) the couple ( $V, E_{s}$ ) is the union of distinct loops;
2) the couple ( $V, E_{d}$ ) is a directed graph containing no loops.

Now we fix $V$ to be a set of five vertices. Let $\left(V, E_{d}, E_{s}\right)$ be a DS-graph. Associate it with a monomial $M\left(V, E_{d}, E_{s}\right)$ in 20 variables, write $t_{i, j}$ with $i, j=1,2, \ldots, 5$ and $i \neq j$. That is

$$
M\left(V, E_{d}, E_{s}\right):=\prod_{(i, j) \in E_{d}} t_{i, j}^{5} \prod_{(i, j) \in E_{s}} t_{i, j}
$$

As usual, two DS-graphs will be viewed isomorphically if they differ exactly by a permutation on the vertices. Denote by $\mathrm{DS}(5)$ the set of all isomorphism class of DS-graphs associated to the set of vertices $V$. For a monomial $m$ in 20 variables $t_{i, j}$, we denote $\sum_{\text {sym }} m$ the symmetric sum of $m$, namely,

$$
\sum_{\operatorname{sym}} m:=\sum_{\sigma \in S_{5}} \sigma(m) .
$$

We are in the position to describe a basis of the quotient $\mathbb{C}\left[t_{i, j}\right]^{G}$.
Theorem 5. The quotient $\mathbb{C}\left[t_{i j}\right]^{G}$ is generated by the polynomials $\sum_{\text {sym }} M\left(V, E_{d}, E_{s}\right)$ with $\left(V, E_{d}, E_{s}\right) \in \mathrm{DS}(5)$.

Proof. Let $P$ be a polynomial in $\mathbb{C}\left[t_{i j}\right]^{G}$. Since $P$ is invariant under symmetric group, one may write

$$
P=\sum_{\text {sym }} P_{1}+\ldots+\sum_{\text {sym }} P_{k}
$$

where all $P_{s}$ 's are monomials. By assumption, $P_{i}$ is invariant under action of subgroup $\{i d\} \times \mathbb{Z}_{5}^{5}$. We see that $P_{s}$ can be split into three parts

$$
\begin{equation*}
P_{s}=\prod_{i=1}^{5}\left(t_{i, j}^{5}\right)^{e_{i, j}} \cdot \prod_{\left\{i_{j}\right\}}\left(t_{i_{1}, i_{2}} t_{i_{2}, i_{3}} \cdots t_{i_{n-1}, i_{n}} t_{i_{n}, i_{1}}\right) \cdot R \tag{2}
\end{equation*}
$$

Geometrically, the second part is represented by loops. Hence, we may assume that $R=\lambda t_{i_{1}, j_{1}} t_{i_{2}, j_{2}} \ldots t_{i_{m}, j_{m}}$ contains no loops. That means

$$
i_{1} \notin\left\{j_{1}, j_{2}, j_{3}, \ldots, j_{m}\right\}
$$

However, $R$ is not invariant under $\{i d\} \times \mathbb{Z}_{5}^{5}$ if $m \geqslant 1$. Thus, we have $R=$ $\lambda$. Suppose that all power $e_{i, j}$ 's in the expression of $P_{s}$ equal 1 and the second part consists of distinct loops. Then clearly the polynomial $P_{s}$ is given by some DS-graph $\left(V, E_{d}, E_{s}\right)$. That is $P_{s}=M\left(V, E_{d}, E_{s}\right)$. To complete the proof, it suffices to reduce the powers in (2). Define invariant polynomials

$$
S_{1}:=\sum_{\text {sym }}\left(t_{i, j}^{5}\right)^{2}-\left(\sum_{\mathrm{sym}} t_{i, j}^{5}\right)^{2}
$$

and

$$
S_{2}:=\sum_{\text {sym }}\left(t_{i_{1}, i_{2}} t_{i_{2}, i_{3}} \cdots t_{i_{n-1}, i_{n}} t_{i_{n}, i_{1}}\right)^{2}-\left(\sum_{\text {sym }} t_{i_{1}, i_{2}} t_{i_{2}, i_{3}} \cdots t_{i_{n-1}, i_{n}} t_{i_{n}, i_{1}}\right)^{2}
$$

We find that both $S_{1}$ and $S_{2}$ satisfy the previous condition. Hence they are generated by polynomials represented by DS-graphs. It yields that $\sum_{\text {sym }}\left(t_{i, j}^{5}\right)^{2}$ and $\sum_{\text {sym }}\left(t_{i_{1}, i_{2}} t_{i_{2}, i_{3}} \cdots t_{i_{n-1}, i_{n}} t_{i_{n}, i_{1}}\right)^{2}$ are also represented by DSgraphs. This completes the proof.

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